

Sequence Prediction using Partially-Ordered Episode Rules

Yangming Chen¹, Philippe Fournier-Viger^{1,2},
Farid Nouioua², Youxi Wu³

1 Harbin Institute of Technology (Shenzhen), China

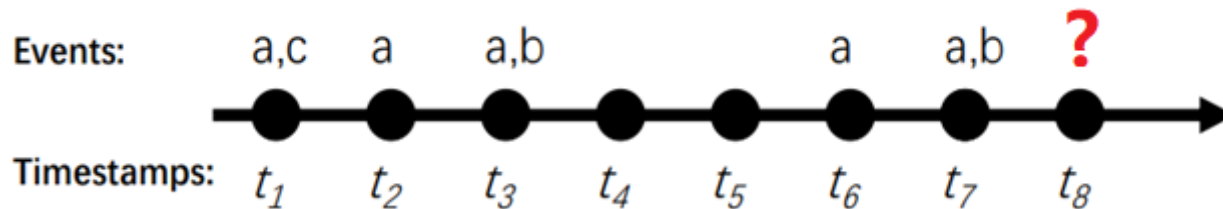
2 Shenzhen University, China

3 University of Bordj Bou Arreridj, Algeria

4 Hebei University of Technology, Tianjin, China

Introduction

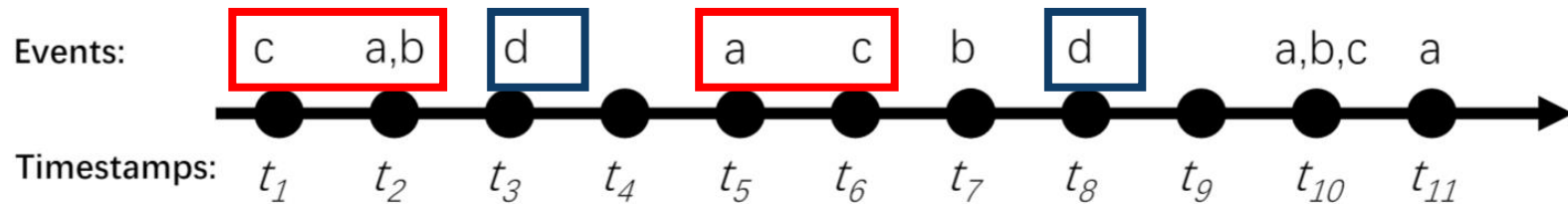
- **Sequence prediction:**
predicting the next event/symbol of a sequence



- **Episode rule mining:** discovering rules to help understand the data or do predictions.
- We compare **three types of rules** for prediction:
 - **Episode rules** (Toivonen et al., 1996)
 - **Precise positioning episode rules** (Ao et al., 2017)
 - **Partially-ordered episode rules** (Fournier-Viger et al., 2021)

Three Types of Episode Rules

1) **Standard episode rule (SER)**: rule where events in the antecedent and in the consequent are ordered (found by MINEPI+ algorithm).



Examples:

The rule $\langle \{c\}, \{a\} \rangle \rightarrow \langle \{d\} \rangle$ has an occurrence in time interval $[t_1, t_3]$

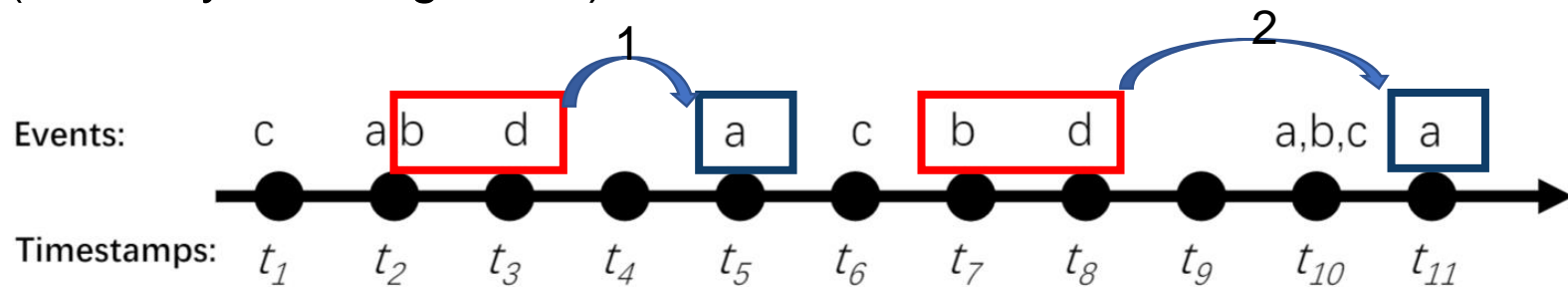
The rule $\langle \{a\}, \{c\} \rangle \rightarrow \langle \{d\} \rangle$ has an occurrence in time interval $[t_5, t_8]$

Support: How many times a rule appears

Confidence: The conditional probability that the antecedent is followed by the consequent

Three Types of Episode Rules

2) Precise-Positioning Episode rule (PER): rule where the elapsed time between the antecedent and the consequent is fixed (found by PRU algorithm).



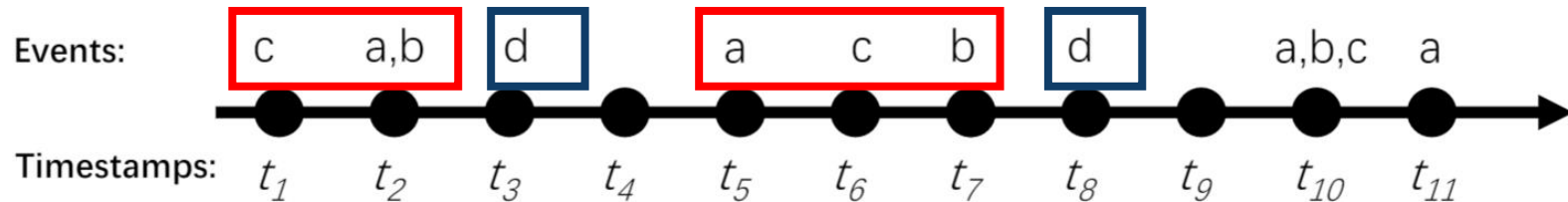
Examples:

The rule $\langle \{b\}, \{d\} \rangle \xrightarrow{1} \langle \{a\} \rangle$ has an occurrence in time interval $[t_2, t_5]$

The rule $\langle \{b\}, \{d\} \rangle \xrightarrow{2} \langle \{a\} \rangle$ has an occurrence in time interval $[t_7, t_{11}]$

Three Types of Episode Rules

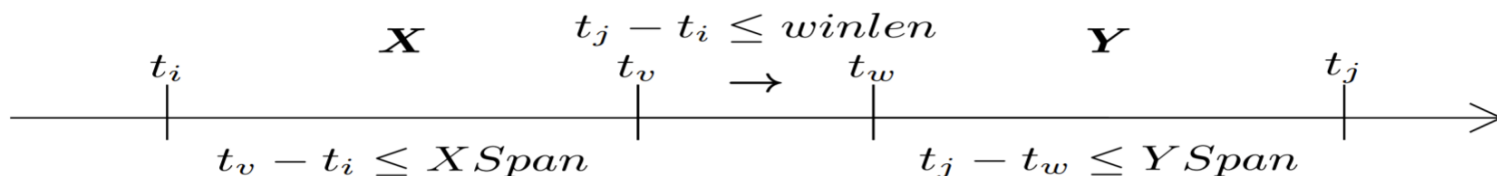
3) Partially-Ordered Episode Rules (POER): rule where events in the antecedent and in the consequent are unordered (found by POERM algorithm).



Example:

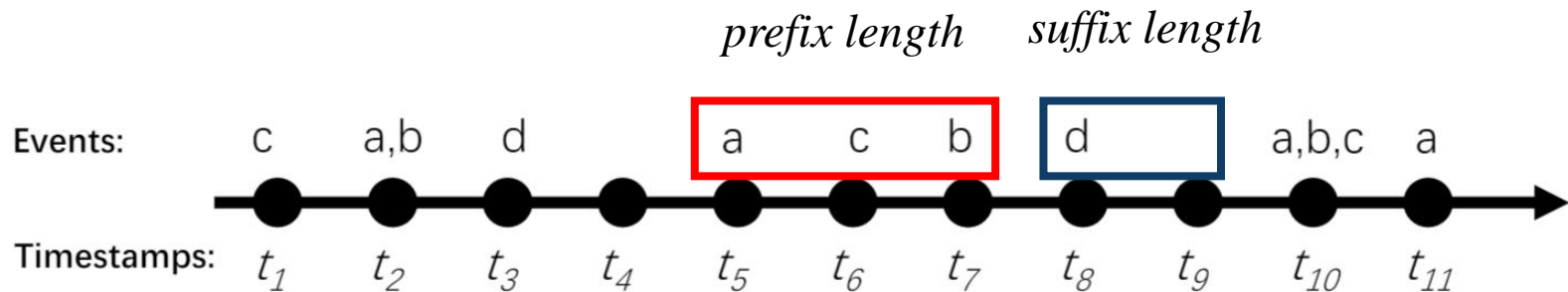
The rule $\langle \{a,b,c\} \rangle \rightarrow \langle \{d\} \rangle$ has occurrences in $[t_1, t_3]$ and $[t_5, t_8]$.

minsup= 3, minconf= 0.6, XSpan= 3, winlen= 4, YSpan= 1



Sequence Prediction

Goal: predict an event that will appear in the *suffix* of a sequence given the events observed in the *prefix*.



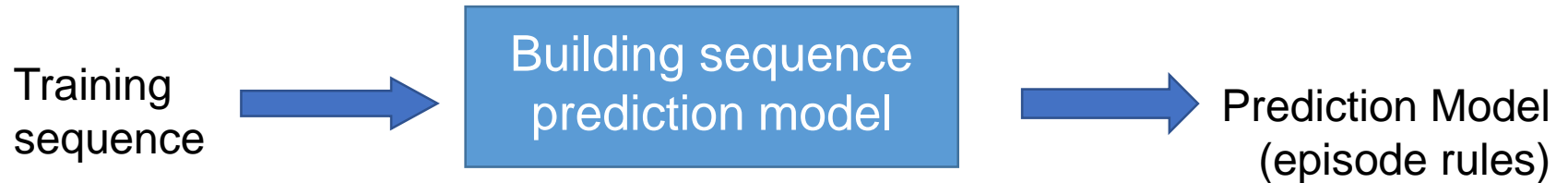
Possible outcomes:

- Good prediction
- Wrong prediction
- Unable to make a prediction (no match)

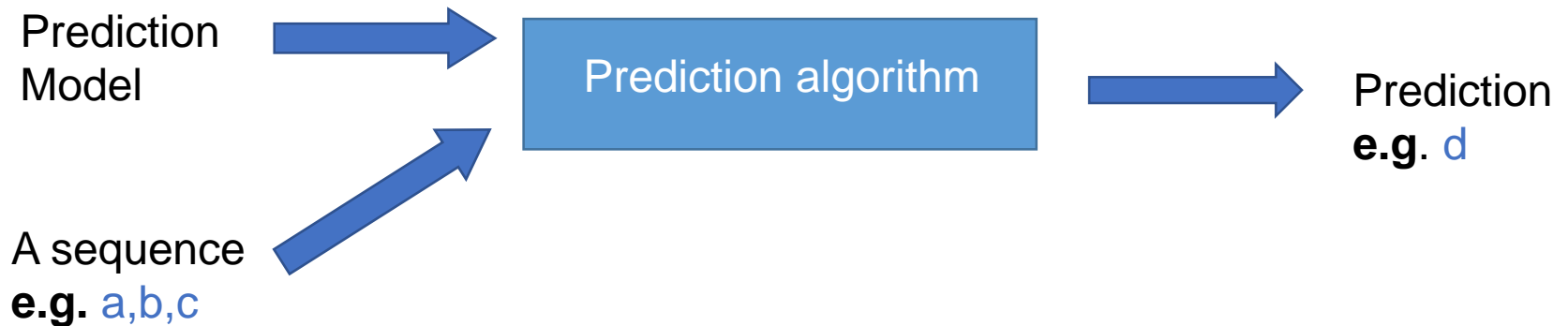


3. The EpisodePredictor Framework

Phase 1) Training



Phase 2) Prediction





4 Experimental Evaluation

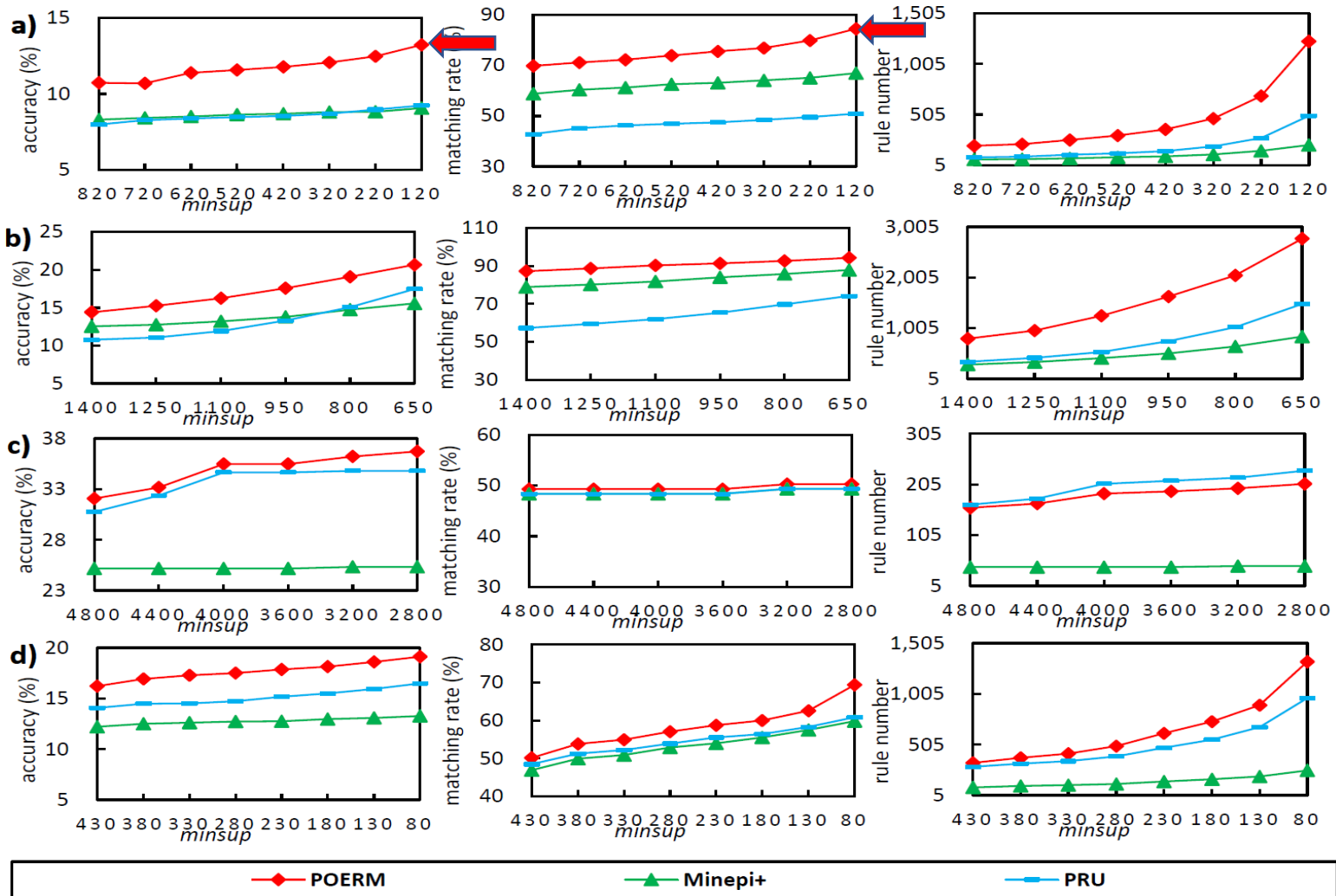
Dataset and Default Values

Dataset	# Timestamps	# Events
Bible	649,024	13,905
OnlineRetail	2,364,798	2,603
FIFA	710,435	2,990
Leviathan	153,682	9025

Default Values	minsup	minconf	prefixSize	suffixSize
Bible	120	0.3	4	1
OnlineRetail	650	0.3	4	1
FIFA	2800	0.3	2	2
Leviathan	80	0.3	2	2



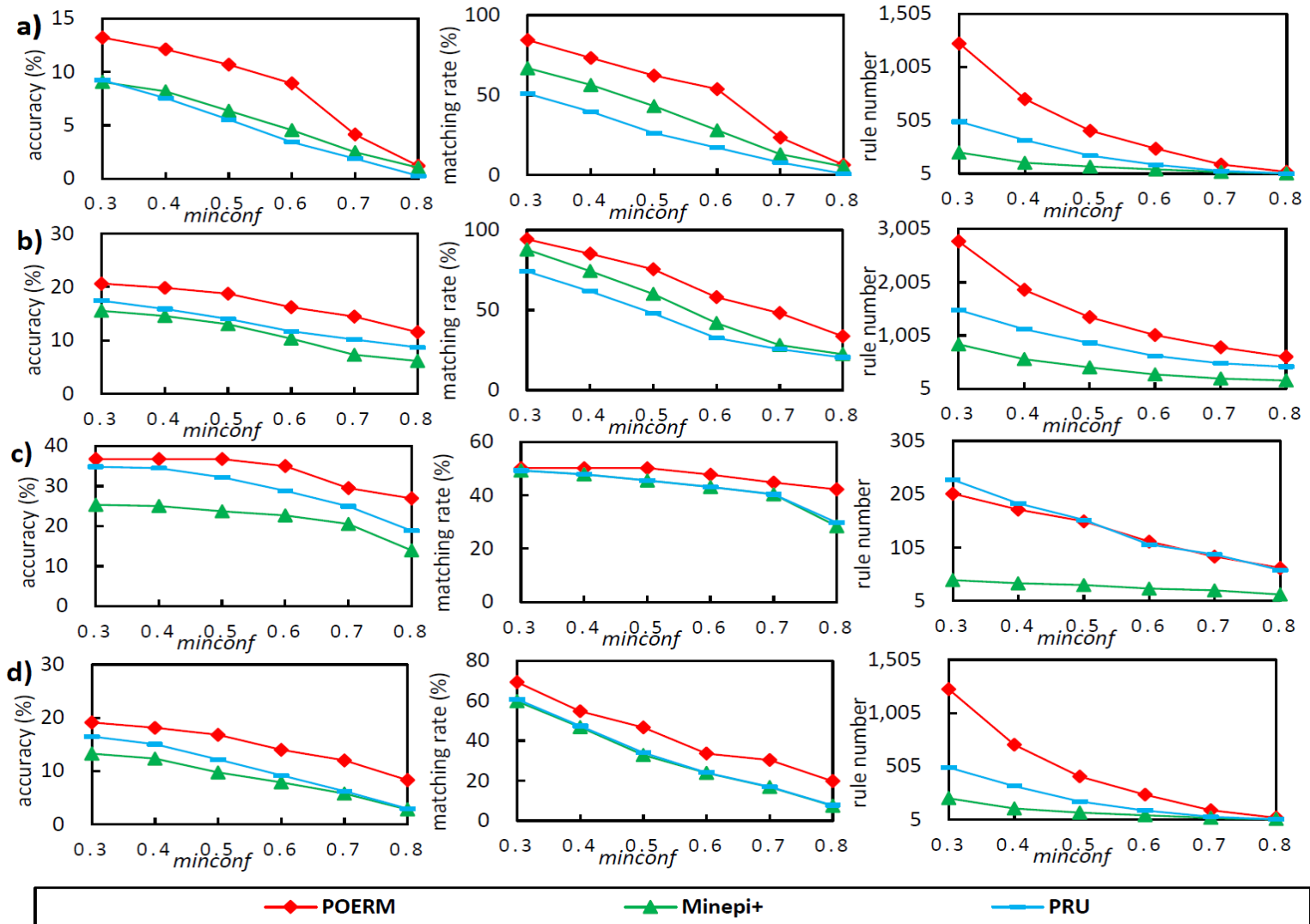
4. Experimental Evaluation (Influence of *minsup*)



Generally, $\uparrow \text{minsup} \Rightarrow \uparrow \text{rule count}, \uparrow \text{matching rate}, \uparrow \text{accuracy}$
Partially-ordered episode rules have the best results.



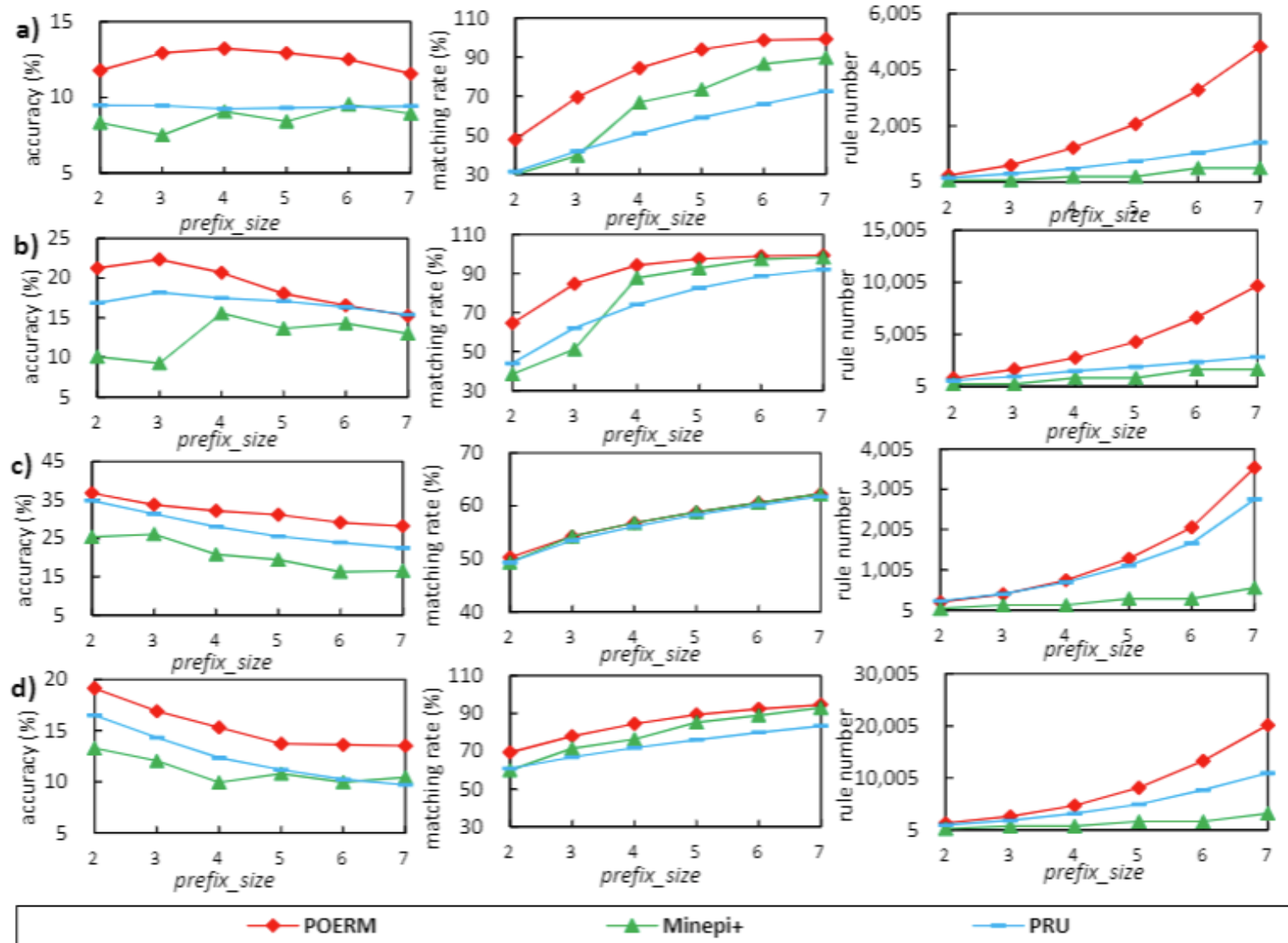
4. Experimental Evaluation (Influence of *minconf*)



Generally, $\uparrow \text{minconf} \Rightarrow \downarrow \text{rule count}, \downarrow \text{matching rate}, \downarrow \text{accuracy}$



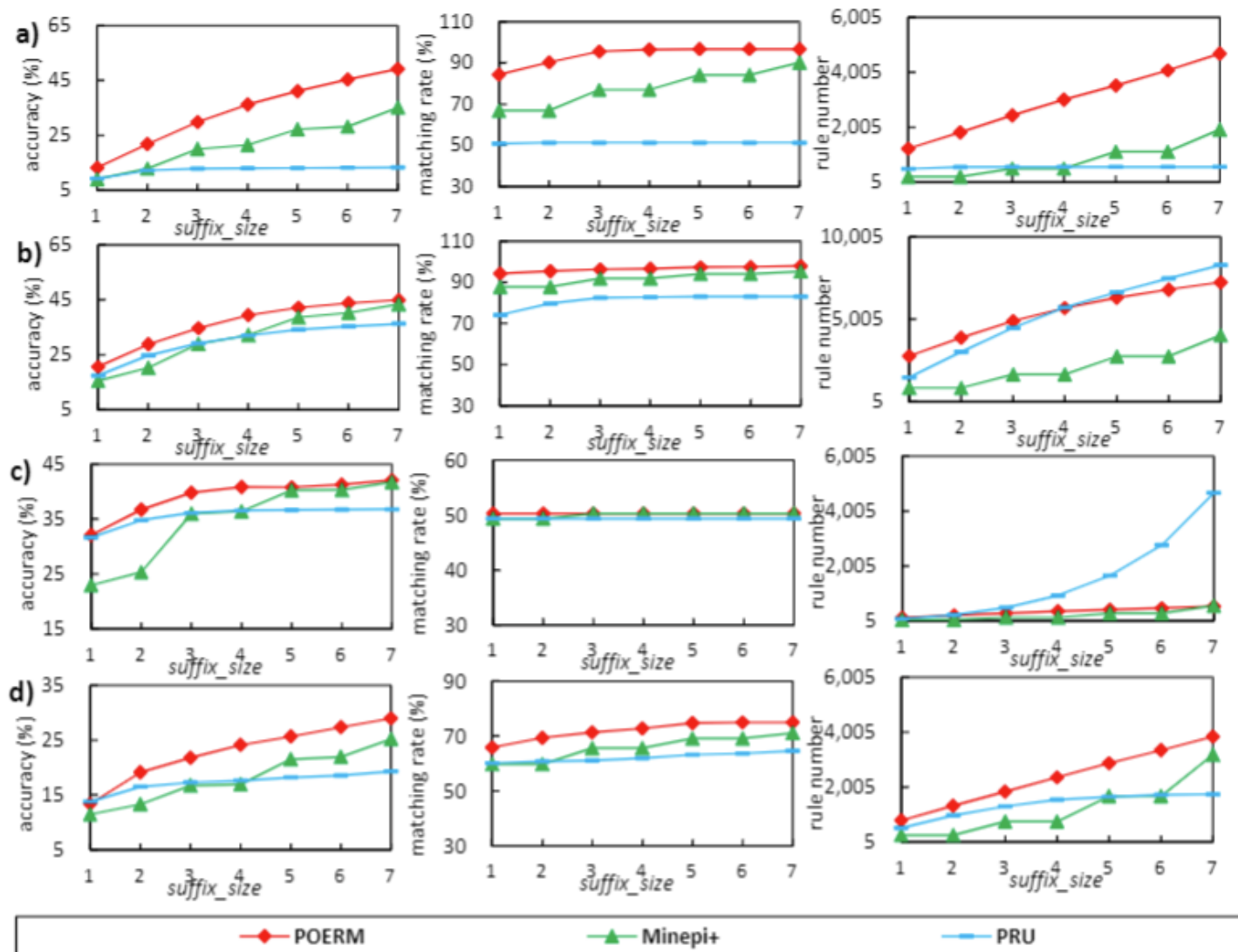
4. Experimental Evaluation (Influence of *prefix size*)



Generally, \uparrow prefix size \Rightarrow \uparrow rule count, \uparrow matching rate, \uparrow \downarrow accuracy



4. Experimental Evaluation (Influence of *suffix* size)



Generally, \uparrow suffix size \Rightarrow \uparrow rule count, \uparrow matching rate, \uparrow accuracy



5. Conclusion

•Contributions:

- utilize a new type of episode rules, named **partially-ordered episode rules to improve** sequence prediction
- Better results are obtained in terms of **accuracy and matching** rate compared to two popular types of episode rules

•Future work:

- Episode rule-based sequence prediction models for more complex event sequences.
- Design an incremental episode rule mining algorithm to decrease runtime performance in dynamic environment

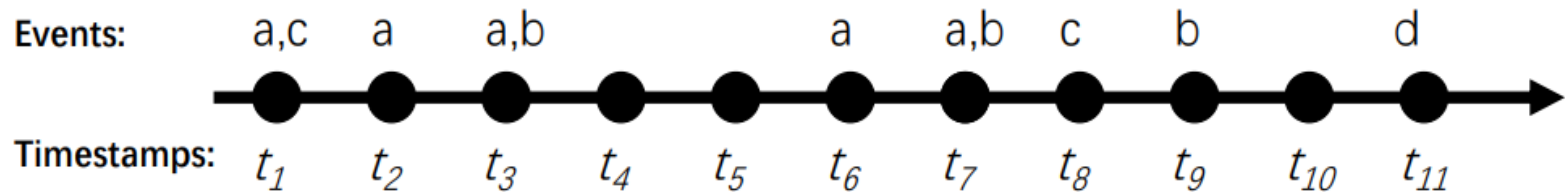
➤Open-source code, datasets:

- [SPMF data mining library](#) (over 200 algorithms)

Thanks for listening!

Frequent Episode Mining

Input: a sequence of events with timestamps



Output:

All frequent episode
(*minimal occurrence* \geq *minSup*)

For example:

episode $\langle \{a,b\}, \{c\} \rangle$

Episode types:

parallel episodes, serial
episodes, complex
episodes

Algorithms:

WINEPI, MINEPI, EMMA, MINEPI+, ...